- What is distributed programming?
- What are some problems it's used for?
- How is it organized?
 - Multiple computers under the same management
 - Multiple computers run by different entities
- What are issues that must be solved?
- Examples
 - Seti@Home / BOINC
 - Google's map/reduce
 - Teraflop-scale processors

What Is It Used for?

- Large-scale scientific problems
 - Finite element models: simulate reality by following the laws of physics at each of millions of points
 - Weather modeling
 - Structural analysis
 - Earthquakes
 - Biochemistry models (protein folding, DNA sequencing)
- Large-scale searching
 - Internet
 - Store and search a piece of the Web on each node
 - Results are combined and returned
- Signal processing
 - Look for features in terabytes of signal

History of High-Performance Computing

- 1946: ENIAC (Electronic Numerical Integrator And Computer)
- 1960: Network of vacuum-tube computers US Air Force (SAGE)
- 1985-95: Supercomputers (Convex, Cray, Thinking Machines)
- 1985: VAX VMS clusters by Digital Equipment Corporation
- 1990: Clusters of Unix workstations (HP, SGI, SUN)
- 1990-95: Transputers by Inmos and Parsytec
- 1995-00: Beowulf concept: Linux based low budget PC's
- 2000-: Linux clusters: Linux based (very) high budget PC's

ENIAC



Osaka University Vacuum Tube Computer



CRAY X-MP/24



- Beowulf: Name of the first Linux cluster by NASA in 1994
- Main goal: high and reliable computing power at low costs
- Features:
 - Based upon standard off-the-shelf Intel PCs
 - Operating system Linux (sometimes with special drivers)
 - Dedicated interconnecting network (no external traffic allowed)
 - Master server accessible from outside and through monitor/keyboard
 - Other nodes (Slaves) only equipped with a network card
 - Master NFS shared file system: code transparent on all slaves
 - Message passing software: mostly MPI and PVM

- Advantages
 - Hardware cheap compared with workstations or supercomputers
 - Software is mostly open source and free (Linux, MPI, PVM, GCC)
 - Easy to expand with new systems or join with other clusters
 - Many choices for the interconnecting network
 - Very reliable and stable (but depends on hardware)
- Disadvantages
 - PC hardware less reliable than workstation or supercomputer
 - Depending on network: higher latencies (e.g. for TCP/IP)
 - Failure detection on cluster nodes difficult (no monitor/keyboard)
 - Single entry point: only master accessible from outside

- Types of interconnecting networks
 - Serial or RS323 port connections or SLIP (0.1 Mb/s , 100 ms)
 - Parallel port connections or PLIP (1 Mb/s , 100 ms)
 - Ethernet 10Mbit, 100Mbit (10-100 Mb/s , 100 $\mu s)$
 - Ethernet Gigabit (1 Gb/s , 200 $\mu s)$
 - Shared versus Switched network routers
 - Dedicated low latency network cards:
 - Myrinet (10 Gb/s, 2 $\mu s)$ and Infiniband (2 Gb/s/channel, 1 $\mu s)$

Computing Cluster at The American Museum of Natural History in New York City



Cluster of PCs at The ORNL - The Stone Souper Computer



HP BladeSystem c7000 Populated with 16 Blades



IBM Roadrunner - 1.1 Petaflop Supercomputer



12,960 IBM PowerXCell 8i CPUs and 6,480 AMD Opteron dual-core processors

- Several available programming styles
 - Message-passing
 - Object-based
 - "Work packets"
- Each is best suited for different kinds of problems
 - Often, there's overlap between programming styles
 - Choice depends on how tightly coupled the program must be

- Coupling is the amount of coordination that individual nodes must have with each other
- Loosely coupled: not much coordination
 - Task can be neatly divided into pieces
 - Individual pieces don't have much to do with one another
 - Results combined at the end
- Tightly coupled: closer coordination between nodes
 - Intermediate results depend on those from other nodes
 - Communication occurs frequently
 - Nodes need to be somewhat synchronized so one node doesn't get ahead of others

Message Passing

- Work divided among nodes
- Nodes communicate via messages as needed
 - MPI (Message Passing Interface) commonly used
- Messages used to
 - Synchronize nodes
 - Parcel out work
 - Communicate intermediate results
- Code on individual nodes often, but not always the same
 - Typically, data is divided among nodes
 - Sometimes, functionality is divided
 - Mail filtering and delivery
 - Large-scale web service (DB, session handling, page serving)

- Similar to message passing
- Each object does its own processing locally
- Remote methods work like you'd expect
 - Remote objects run computations
- Typically slower for large-scale computations
 - Distributed objects usually synchronous
 - Easier to move data rather than moving small chunks of computation
- May get used in systems where function is different for each node

- Computation divided into many small independent pieces
 - Monte Carlo simulation
 - SETI
 - Large number factoring (decryption)
- Each node takes some units of work
 - Units are independent
 - Node completes them, reports back to coordinator
- Coordinator tracks who's doing what
 - Reschedules work that hasn't been done yet
 - Failures handled by redoing work units

Distributed Computing Organization

- Computers largely identical
 - Owned by a single organization
 - Configured the same way
 - Comparable abilities (speed, I/O, etc.)
- Computers somewhat different
 - Controlled by a single organization
 - Configured similarly
 - May have widely disparate abilities or network speeds
- Computers unrelated
 - Owned by different organizations
 - Configured differently
 - About the only constant is free CPU time

- Often called parallel computing, especially if nodes connected by high-speed networks
- Same environment everywhere
 - Tools & binaries available on every node
 - File system looks the same everywhere
- Security provided by
 - Single username across nodes
 - Security at the "front door"
- Good for large-scale scientific workloads
- Typically very expensive!

- Computers under single administrative domain
 - Similar available resources (users, files)
 - No worries about malicious nodes that might corrupt results
- Computers have different capabilities
 - Some nodes are much faster than others
 - Computation can't proceed in "lock-step"
 - Need to take differences into account in scheduling
- May be able to use spare cycles on workstations along with "centralized" resources
 - "Night-time supercomputer"
- Jobs managed centrally
- Good fit for loosely coupled problems

- No common configuration or administration
 - Different user name at each location
 - No set of common resources except those brought along explicitly
 - Capabilities wildly different
- Security issues
 - Malicious nodes might run the program incorrectly
 - Malicious nodes might steal your data!
- Communication can be dicey
 - Nodes may have slow network connections (or even fail)
 - Failures have to be handled by a coordinator
- Typically only done with "work units"

- Need to take a big problem and chop it up
- Divide it arbitrarily
 - Job has n things that need to be done
- Divide it up "physically"
 - Usually works with problems that simulate the real world
 - Pieces correspond to regions of the phenomenon being simulated
 - May run into problems if some pieces are harder than others
- Divide it up into multiple runs
 - May rerun the same simulation lots of times (Monte Carlo method)
 - Simulations are largely independent

- Each node does a small part of the work
- Results need to be combined
 - Assembled: "concatenate" results together with no additional processing: common for physical problems
 - Reduced: results from individual nodes are "merged"
 - Search
 - Simulations
- This part of the program is difficult to speed up

- Distributed systems have to work together
- Who decides how they do this?
- Single (central) coordinator
 - Simple to program
 - Less efficient: central bottleneck
 - Prone to failure
- Multiple central coordinators
 - Must coordinate amongst themselves
 - More scalable than single coordinator
- Fully distributed: nodes coordinate amongst themselves
 - Difficult to program
 - Most efficient approach

- Every node needs to run the right code!
 - Easy in a tightly coupled system
 - Difficult in a loosely coupled system, especially if it's run by multiple organizations
- Solution: require each node to run code that loads other code as needed
 - Java Virtual Machine
 - Local daemon that downloads binaries as needed
- Solution: use a distributed file system
 - Every node can get the code it needs
 - Use the Web for this...

- Two security challenges
 - Protect system from code running on it
 - Protect running code from the rest of the system
- Protecting the system from the distributed code
 - Trust the code?
 - Big risk
 - Limit privileges
 - Run as a user that has few (if any) abilities on the system
 - Restrict CPU usage
- Protecting the distributed code from the system
 - Prevent data and computation from corruption
 - Prevent the system from stealing the data (yes, this is a real issue in many distributed systems)

- Google has an index of the entire Internet (or at least a lot of it)
- Index is too large to fit on a single machine
 - Hundreds of terabytes of data
 - Thousands of disks
- Too much activity for only a single server
 - Need to divide the problem up
 - Handle requests on multiple servers
- Divide up data and requests

- Divide Web index by batches of pages
 - Crawl the Web continuously
 - Each set of pages is on a single machine
 - Each machine has indices for all words in those pages
- Queries go to all machines
 - Quickly search individual machines for set of pages
 - Results merged separately
- Failures handled by ignoring that part of the Web
 - It'll be recrawled soon anyway
 - Recently, some redundancy was included

- Google's approach is called map/reduce
 - Computation is mapped to all of the nodes
 - Results from all nodes are combined (reduced) into a single result set
 - Uses specialized coordinators to do it
- Google has techniques to do this quickly!
 - Make individual nodes fast
 - Redo computations that fail (or just don't respond)
- Google's file system is optimized for this
 - Special operations for appending to large files
 - Optimized for dealing with gigabyte files
 - Not good for smaller stuff....

- BOINC is a system for doing distributed computation across a large set of unrelated nodes
 - Distribute small units of computation to individual (home) computers
 - Gather results from them
- Platform is designed to run any software that can break up computation this way
 - SETI
 - Protein folding
 - Climate change

BOINC Details

- Jobs divided into very small tasks
 - Search a small portion of the sky
 - Try several protein folding combinations
- Clients download
 - Software for a particular task
 - List of small tasks to run
 - Data for the small tasks
- Clients run the software on the small tasks
 - Respond back with results when they're finished
- Coordinator ships out tasks and collates results
 - Often hands tasks to multiple computers
 - Check accuracy
 - Deal with failure

More on **BOINC**

- System is open: others can create new programs to run across the world
- System runs on multiple platforms
 - Deal with byte ordering
 - Different assembly languages (PowerPC, x86, etc.)
 - Wide range of different speeds
- Reliability isn't so great
- Must be very loosely coupled
 - No guarantee on how long each task will take
 - Communication may be spotty
 - Data is not sensitive (no worry about client stealing it)

- Lack of shared memory, necessity to send messages
- Basic operations: Send() and Receive()
 - Client sends a request and waits for an answer
 - Server receives the request and sends a response
- Messages can be reliable or unreliable (when unreliable, higher layer must provide reliability of transmission)
- Can be based on a specialized protocol or a generalpurpose protocol (such as TCP/IP)

OSI Reference Model

Created by Josef Sábl for wikipedia.org - please send any suggestions or corrections to josef.sabl@post.cz

Standard for the transmission of IP datagrams on avian carriers Implementation: http://www.blug.linux.no/rfc1149/

Script started on Sat Apr 28 11:24:09 2001 vegard@gyversalen:~\$ /sbin/ifconfig tun0 tun0 Link encap:Point-to-Point Protocol inet addr:10.0.3.2 P-t-P:10.0.3.1 Mask:255.255.255.255 UP POINTOPOINT RUNNING NOARP MULTICAST MTU:150 Metric:1 RX packets:1 errors:0 dropped:0 overruns:0 frame:0 TX packets:2 errors:0 dropped:0 overruns:0 carrier:0 collisions:0 RX bytes:88 (88.0 b) TX bytes:168 (168.0 b)

vegard@gyversalen:~\$ ping -i 900 10.0.3.1 PING 10.0.3.1 (10.0.3.1): 56 data bytes 64 bytes from 10.0.3.1: icmp_seq=0 ttl=255 time=6165731.1 ms 64 bytes from 10.0.3.1: icmp_seq=4 ttl=255 time=3211900.8 ms 64 bytes from 10.0.3.1: icmp_seq=2 ttl=255 time=5124922.8 ms 64 bytes from 10.0.3.1: icmp_seq=1 ttl=255 time=6388671.9 ms

--- 10.0.3.1 ping statistics ---9 packets transmitted, 4 packets received, 55% packet loss round-trip min/avg/max = 3211900.8/5222806.6/6388671.9 ms vegard@gyversalen:~\$ exit

Script done on Sat Apr 28 14:14:28 2001

Implementation of Layers

Information Transfer

Exercise 1

- Implement a server computing roots of real numbers and providing current date and time on server
- Based on TCP protocol
- To ensure portability between different processors, transmit all numbers in Big Endian format
- RQ ID allows to distinguish different requests

Request for square root:

0 0 0 1 RQ ID	Number (IEEE double)
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Response:

1	0	0	1	RQ ID	Root (IEEE double)
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Exercise 1

- Date and time sent in textual form, without terminating zero
- Length sent in Big Endian format
- During one connection several requests can be sent
- Order of responses can be different than order of requests

Request for time and date:

0	0	0	2	RQ ID
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Response:

1 0 0 2 RQ ID Length (BE) Time and dat
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